Bayesian Structured Hazard Regression

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Outline

- Leukemia survival data.
- Structured hazard regression for survival times.
- Bayesian inference in structured hazard regression.
 - Full Bayesian inference based on MCMC.
 - Empirical Bayes inference using mixed model methodology.
- Multi-state models for the analysis of human sleep.

Leukemia Survival Data

- Survival time of adults after diagnosis of acute myeloid leukemia.
- 1,043 cases diagnosed between 1982 and 1998 in Northwest England.
- 16 % (right) censored.
- Continuous and categorical covariates:
 - age age at diagnosis,
 - wbc white blood cell count at diagnosis,
 - sex sex of the patient,
 - tpi Townsend deprivation index.
- Spatial information in different resolution.



• Classical Cox proportional hazards model:

$$\lambda(t;x) = \lambda_0(t) \exp(x'\gamma).$$

- Baseline hazard $\lambda_0(t)$ is a nuisance parameter and remains unspecified.
- Estimate γ based on the partial likelihood.
- Questions / Limitations:
 - Simultaneous estimation of baseline hazard rate and covariate effects.
 - Flexible modelling of covariate effects (e.g. nonlinear effects, interactions).
 - Spatially correlated survival times.
 - Non-proportional hazards models / time-varying effects.
- \Rightarrow Structured hazard regression models.

• Replace usual parametric predictor with a flexible semiparametric predictor

$$\lambda(t;\cdot) = \lambda_0(t) \exp[f_1(age) + f_2(wbc) + f_3(tpi) + f_{spat}(s_i) + \beta_1 sex]$$

and absorb the baseline

$$\lambda(t; \cdot) = \exp[g_0(t) + f_1(age) + f_2(wbc) + f_3(tpi) + f_{spat}(s_i) + \beta_1 sex]$$

where

- $g_0(t) = \log(\lambda_0(t))$ is the log-baseline hazard,
- f_1, f_2, f_3 are nonparametric functions of age, white blood cell count and deprivation, and
- f_{spat} is a spatial function.









Structured Hazard Regression

- A general structured hazard regression model consists of an arbitrary combination of the following model terms:
 - Log baseline hazard $g_0(t) = \log(\lambda_0(t))$.
 - Time-varying effects $g_l(t)u_l$ of covariates u_l .
 - Nonparametric effects $f_j(x_j)$ of continuous covariates x_j .
 - Spatial effects $f_{spat}(s)$ of a spatial location variable s.
 - Interaction surfaces $f_{j,k}(x_j, x_k)$ of two continuous covariates.
 - Varying coefficient interactions $u_j f_k(x_k)$ or $u_j f_{spat}(s)$.
 - Frailty terms b_g (random intercept) or $x_j b_g$ (random slopes).

- Penalised splines for the baseline effect, time-varying effects, and nonparametric effects:
 - Approximate f(x) (or g(t)) by a weighted sum of B-spline basis functions

$$f(x) = \sum \xi_j B_j(x).$$

- Employ a large number of basis functions to enable flexibility.
- Penalise differences between parameters of adjacent basis functions to ensure smoothness:

$$Pen(\xi|\tau^2) = \frac{1}{2\tau^2} \sum (\Delta_k \xi_j)^2.$$

- Bayesian interpretation: Assume a k-th order random walk prior for ξ_j , e.g.

$$\xi_j = \xi_{j-1} + u_j, \quad u_j \sim N(0, \tau^2) \quad (\mathsf{RW1}).$$

$$\xi_j = 2\xi_{j-1} - \xi_{j-2} + u_j, \quad u_j \sim N(0, \tau^2) \quad (\mathsf{RW2}).$$



- **Bivariate** Tensor product P-splines for interaction surfaces:
 - Define bivariate basis functions (Tensor products of univariate basis functions).
 - Extend random walks on the line to random walks on a regular grid.



- Spatial effects for regional data $s \in \{1, \ldots, S\}$: Markov random fields.
 - Bivariate extension of a first order random walk on the real line.
 - Define appropriate neighbourhoods for the regions.
 - Assume that the expected value of $f_{spat}(s) = \xi_s$ is the average of the function evaluations of adjacent sites:

$$\xi_s | \xi_{s'}, s' \neq s, \tau^2 \sim N\left(\frac{1}{N_s} \sum_{s' \in \partial_s} \xi_{s'}, \frac{\tau^2}{N_s}\right).$$





- Spatial effects for point-referenced data: Stationary Gaussian random fields.
 - Well-known as Kriging in the geostatistics literature.
 - Spatial effect follows a zero mean stationary Gaussian stochastic process.
 - Correlation of two arbitrary sites is defined by an intrinsic correlation function.
 - Can be interpreted as a basis function approach with radial basis functions.



- Cluster-specific frailty terms:
 - Account for unobserved heterogeneity.
 - Easiest case: i.i.d Gaussian frailty.
- All covariates in the discussed model terms are allowed to be piecewise constant time-varying.

Bayesian Inference

• Generic representation of structured hazard regression models:

$$\lambda(t) = \exp\left[x(t)'\gamma + f_1(z_1(t)) + \ldots + f_p(z_p(t))\right]$$

• For example:

 $f(z(t)) = b_q$

- $\begin{array}{ll} f(z(t)) = g(t) & z(t) = t & \text{log-baseline effect,} \\ f(z(t)) = u(t)g(t) & z(t) = (u,t) & \text{time-varying effect of } u(t), \\ f(z(t)) = f(x(t)) & z(t) = x(t) & \text{smooth function of a continuous} \\ f(z(t)) = f_{spat}(s) & z(t) = s & \text{spatial effect,} \\ f(z(t)) = f(x_1(t), x_2(t)) & z(t) = (x_1(t), x_2(t)) & \text{interaction surface,} \end{array}$
 - i.i.d. frailty b_g , g is a grouping index.
- The generic representation facilitates description of inferential details.

z(t) = g

- Thomas Kneib
- All vectors of function evaluations f_j can be expressed as

$$f_j = Z_j \xi_j$$

with design matrix Z_j , constructed from $z_j(t)$, and regression coefficients ξ_j .

• Generic form of the prior for ξ_j :

$$p(\xi_j | \tau_j^2) \propto (\tau_j^2)^{-\frac{k_j}{2}} \exp\left(-\frac{1}{2\tau_j^2} \xi_j' K_j \xi_j\right)$$

- $K_j \ge 0$ acts as a penalty matrix, $\operatorname{rank}(K_j) = k_j \le d_j = \dim(\xi_j)$.
- $\tau_j^2 \ge 0$ can be interpreted as a variance or (inverse) smoothness parameter.
- Relation to penalized likelihood: Penalty terms

$$P_{\lambda_j}(\xi_j) = \log[p(\xi_j | \tau_j^2)] = -\frac{1}{2} \lambda_j \xi'_j K_j \xi_j, \qquad \lambda_j = \frac{1}{\tau_j^2}.$$

• Likelihood for right censored survival times under the assumption of noninformative censoring:

$$\prod_{i=1}^{n} \lambda_i (T_i)^{\delta_i} \exp\left(-\int_0^{T_i} \lambda_i(t) dt\right),$$

where δ_i is the censoring indicator.

• In general, numerical integration has to be used to evaluate the cumulative hazard rate (e.g. the trapezoidal rule).

Fully Bayesian inference based on MCMC

• Assign inverse gamma prior to τ_j^2 :

$$p(\tau_j^2) \propto \frac{1}{(\tau_j^2)^{a_j+1}} \exp\left(-\frac{b_j}{\tau_j^2}\right).$$

 $\begin{array}{ll} \mbox{Proper for} & a_j > 0, \ b_j > 0 & \mbox{Common choice: } a_j = b_j = \varepsilon \ \mbox{small.} \\ \mbox{Improper for} & b_j = 0, \ a_j = -1 & \mbox{Flat prior for variance } \tau_j^2, \\ & b_j = 0, \ a_j = -\frac{1}{2} & \mbox{Flat prior for standard deviation } \tau_j. \end{array}$

- Conditions for proper posteriors in structured hazard regression: Enough uncensored observations and either
 - proper priors for the variances or
 - $-a_j < b_j = 0$ and rank deficiency in the prior for ξ_j not too large.

- MCMC sampling scheme:
 - Metropolis-Hastings update for ξ_j :

Propose new state from a multivariate Gaussian distribution with precision matrix and mean

$$P_j = Z'_j W Z_j + \frac{1}{\tau_j^2} K_j$$
 and $m_j = P_j^{-1} Z'_j W (\tilde{y} - \eta_{-j}).$

IWLS-Proposal with appropriately defined working weights W and working observations $\tilde{y}.$

– Gibbs sampler for $au_j^2|$::

Sample from an inverse Gamma distribution with parameters

$$a'_{j} = a_{j} + \frac{1}{2} \operatorname{rank}(K_{j})$$
 and $b'_{j} = b_{j} + \frac{1}{2} \xi'_{j} K_{j} \xi_{j}.$

• Efficient algorithms make use of the sparse matrix structure of P_j and K_j .

Empirical Bayes inference based on mixed model methodology

- Consider the variances τ_i^2 as unknown constants to be estimated.
- Idea: Consider ξ_j a correlated random effect with multivariate Gaussian distribution and use mixed model methodology.
- Problem: In most cases partially improper random effects distribution.
- Mixed model representation: Decompose

$$\xi_j = X_j \beta_j + Z_j b_j,$$

where

$$p(\beta_j) \propto const$$
 and $b_j \sim N(0, \tau_j^2 I_{k_j}).$

 $\Rightarrow \beta_j$ is a fixed effect and b_j is an i.i.d. random effect.

• This yields the variance components model

$$\lambda(t; \cdot) = \exp\left[x'\beta + z'b\right],$$

where in turn

$$p(\beta) \propto const \qquad \text{and} \qquad b \sim N(0,Q).$$

- Obtain empirical Bayes estimates / penalized likelihood estimates via iterating
 - Penalized maximum likelihood for the regression coefficients β and b.
 - Restricted Maximum / Marginal likelihood for the variance parameters in Q:

$$L(Q) = \int L(\beta, b, Q)p(b)d\beta db \to \max_Q.$$

- Involves Laplace approximation to the marginal likelihood (similar as in the previous talk by Håvard Rue).
- Corresponds to REML estimation of variances in Gaussian mixed models.

Human Sleep Data

- Consider individual human sleep data as independent realisations of time-continuous stochastic processes with discrete state space {awake, REM, non-REM}.
- Compact description of such a process in terms of transition intensities between these states.
- Simple approaches: Markov or Semi-Markov processes.
- Limitations / Questions:
 - Changing dynamics of human sleep over night.
 - Individual sleeping habits to be described by covariates.
 - Only a small number of covariates is available (unobserved heterogeneity).
- \Rightarrow Model the transition intensities in analogy to survival models.



time since sleep onset (in hours)

• Simplified structure for the transitions:



• Model for the transitions:

$$\lambda_{AS,i}(t) = \exp\left[\gamma_{0}^{(AS)}(t) + s_{i}\beta^{(AS)} + b_{i}^{(AS)}\right]$$

$$\lambda_{SA,i}(t) = \exp\left[\gamma_{0}^{(SA)}(t) + s_{i}\beta^{(SA)} + b_{i}^{(SA)}\right]$$

$$\lambda_{NR,i}(t) = \exp\left[\gamma_{0}^{(NR)}(t) + c_{i}(t)\gamma_{1}^{(NR)}(t) + s_{i}\beta^{(NR)} + b_{i}^{(NR)}\right]$$

$$\lambda_{RN,i}(t) = \exp\left[\gamma_{0}^{(RN)}(t) + c_{i}(t)\gamma_{1}^{(RN)}(t) + s_{i}\beta^{(RN)} + b_{i}^{(RN)}\right]$$

where

$$\begin{array}{lll} c_i(t) &=& \begin{cases} 1 & \operatorname{cortisol} > 60 \ \mathrm{n} \ \mathrm{mol/l} \ \mathrm{at} \ \mathrm{time} \ t \\ 0 & \operatorname{cortisol} \le 60 \ \mathrm{n} \ \mathrm{mol/l} \ \mathrm{at} \ \mathrm{time} \ t , \\ s_i &=& \begin{cases} 1 & \mathrm{male} \\ 0 & \mathrm{female} , \end{cases} \\ b_i^{(j)} &=& \mathrm{transition-} \ \mathrm{and} \ \mathrm{individual-specific} \ \mathrm{frailty}. \end{array}$$

Human Sleep Data

- Use penalized splines for the baseline and time-varying effects.
- I.i.d. Gaussian priors for the frailty terms (with transition-specific variances).
- The likelihood contribution for individual *i* can be constructed based on a counting process formulation of the model:

$$l_{i} = \sum_{h=1}^{k} \left[\int_{0}^{T_{i}} \log(\lambda_{hi}(t)) dN_{hi}(t) - \int_{0}^{T_{i}} \lambda_{hi}(t) Y_{hi}(t) dt \right]$$

=
$$\sum_{j=1}^{n_{i}} \sum_{h=1}^{k} \left[\delta_{hi}(t_{ij}) \log(\lambda_{hi}(t_{ij})) - Y_{hi}(t_{ij}) \int_{t_{i,j-1}}^{t_{ij}} \lambda_{hi}(t) dt \right].$$

 $N_{hi}(t)$ counting process for type h event.

$$Y_{hi}(t)$$
 at risk indicator for type h event.

- t_{ij} event times of individual i.
- n_i number of events for individal i.
- $\delta_{hi}(t_{ij})$ transition indicator for type h transition.

- \Rightarrow Concepts from survival analysis can be adapted.
 - In particular:
 - Fully Bayesian inference based on MCMC and
 - Mixed model based empirical Bayes inference.

• Baseline effects:



• Time-varying effects for a high level of cortisol:



Software

- Estimation was carried out using BayesX.
- Public domain software package for Bayesian inference in geoadditive and related models.



• Available from

http://www.stat.uni-muenchen.de/~bayesx

Conclusions

- Unified framework for general regression models describing the hazard rate of survival models.
- Bayesian inference based on MCMC or mixed model methodology.
- Extendable to models for transition intensities in multi state models.
- Future work:
 - More general censoring mechanisms.
 - Conditions for propriety of posteriors.
 - Joint modelling of covariates and duration times.

References

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