

On the Distribution of the Adaptive LASSO Estimator – part II

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Outline

- 1 More on penalized LS (ML) estimators.
- 2 Penalized LS with orthogonal design.
- 3 Moving parameter asymptotics and model selection probabilities.
- 4 Computational issues.

Penalized LS (ML) estimators

Linear regression model

$$\mathbf{y} = \theta_1 \mathbf{x}_{.1} + \dots + \theta_k \mathbf{x}_{.k} + \varepsilon$$

- response $\mathbf{y} \in \mathbb{R}^n$
- regressors $\mathbf{x}_{.i} \in \mathbb{R}^n$, $1 \leq i \leq k$
- errors $\varepsilon \in \mathbb{R}^n$
- (unknown) parameter vector $\boldsymbol{\theta} = (\theta_1, \dots, \theta_k)' \in \mathbb{R}^k$

A penalized least-squares (LS) estimator $\hat{\boldsymbol{\theta}}$ for $\boldsymbol{\theta}$ is given by

$$\hat{\boldsymbol{\theta}} = \arg \min_{\boldsymbol{\theta} \in \mathbb{R}^k} \underbrace{\|\mathbf{y} - X\boldsymbol{\theta}\|^2}_{\text{likelihood or LS -part}} + \underbrace{p(\boldsymbol{\theta})}_{\text{penalty}}$$

The penalty function $p(\boldsymbol{\theta})$ involves a tuning parameter λ_n ($\lambda_n = 0$ corresponds to unpenalized/ordinary LS).

$X = [\mathbf{x}_{.1}, \dots, \mathbf{x}_{.k}]$ the $n \times k$ regression matrix.

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Clearly, different penalties give rise to different estimators.

- General class of Bridge-estimators (Frank & Friedman, 1993) using l_γ - type penalties

$$p(\boldsymbol{\theta}) = \lambda_n \sum_{i=1}^k |\theta_i|^\gamma$$

$\gamma = 2$: Ridge-estimator (Hoerl & Kennard, 1970)

$\gamma = 1$: LASSO (Tibshirani, 1996).

- Hard- and soft-thresholding estimators.
- Smoothly clipped absolute deviation (SCAD) estimator (Fan & Li, 2001).
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Bridge-estimators satisfy

$$\min \|y - X\boldsymbol{\theta}\|^2 + \lambda_n \sum_{i=1}^k |\theta_i|^\gamma \quad (0 < \gamma < \infty)$$

For $\gamma \rightarrow 0$, get

$$\min \|y - X\boldsymbol{\theta}\|^2 + \lambda_n \text{card}\{i : \theta_i \neq 0\}$$

which yields a minimum C_p -type procedure such as AIC and BIC.
(l_γ -type penalty with “ $\gamma = 0$ ”)

- For “ $\gamma = 0$ ” procedures are computationally expensive.
- For $\gamma > 0$ (Bridge) estimators are more computationally tractable, especially for $\gamma \geq 1$ (convex objective function).
- For $\gamma \leq 1$, estimators perform model selection

$$P(\hat{\theta}_i = 0) > 0 \quad \text{if } \theta_i = 0$$

Same for SCAD, hard- and soft-thresholding. Phenomenon is more pronounced for smaller γ .

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Linear regression model

$$\mathbf{y} = \theta_1 \mathbf{x}_{\cdot 1} + \dots + \theta_k \mathbf{x}_{\cdot k} + \varepsilon$$

- X is non-stochastic, $n \times k$ and $rk(X) = k$.
- $\varepsilon \sim N_n(0, \sigma^2 \mathcal{I}_n)$
- σ^2 is known (wlog $\sigma^2 = 1$) and $X'X$ is diagonal, in particular $X'X = n\mathcal{I}_k$.

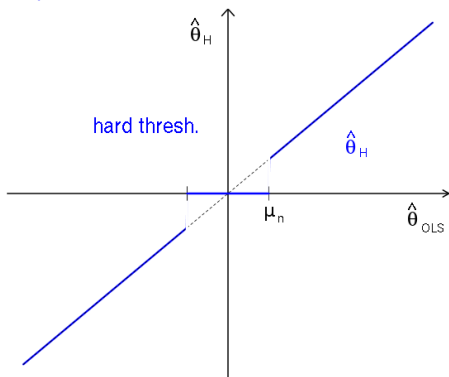
Again, wlog consider **Gaussian location model** $y_1, \dots, y_n \stackrel{\text{iid}}{\sim} N(\theta, 1)$.

Then $\hat{\theta}_{\text{OLS}} = \hat{\theta}_{\text{MLE}} = \bar{y}$ and we want to choose between the **restricted model** $M_R = \{N(0, 1)\}$ or the **full model** $M_U = \{N(\theta, 1) : \theta \in \mathbb{R}\}$.

Hard-thresholding $\hat{\theta}_H$

$$\rho(\theta) = n [\mu_n^2 - (|\theta| - \mu_n)^2 \mathbf{1}(|\theta| < \mu_n)]$$

$$\hat{\theta}_H = \bar{y} \mathbf{1}(|\bar{y}| > \mu_n)$$

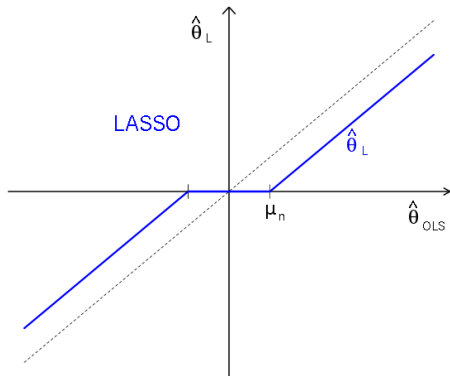


- Equivalent to a post-model estimator based on (eg) t-tests.
- Estimator is not continuous.
- Possesses an “oracle-property” if sparsely-tuned.

Soft-thresholding $\hat{\theta}_L$

$$p(\theta) = 2n\mu_n|\theta|$$

$$\hat{\theta}_L = \text{sign}(\bar{y}) (|\bar{y}| - \mu_n)_+$$

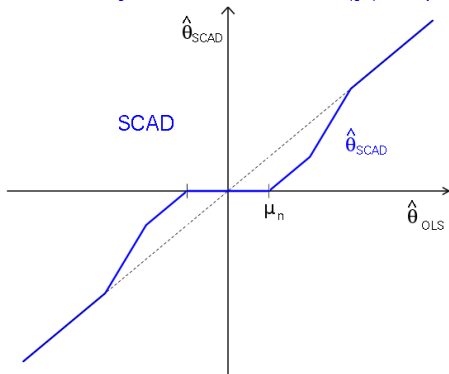


- Equivalent to LASSO.
- Bias problem! No “oracle-property”.

Smoothly-clipped-absolute-deviation $\hat{\theta}_{\text{SCAD}}$

$p'(\theta) = \mu_n [\mathbf{1}(\theta \leq \mu_n) + (a\mu_n - \theta)_+ / ((a-1)\mu_n) \mathbf{1}(\theta > \mu_n)]$,
where $a > 2$ is an additional tuning parameter.

$$\hat{\theta}_{\text{SCAD}} = \begin{cases} \text{sign}(\bar{y})(|\bar{y}| - \mu_n)_+ & \text{if } |\bar{y}| \leq 2\mu_n \\ [(a-1)\bar{y} - \text{sign}(\bar{y})a\mu_n] / (a-2) & \text{if } 2\mu_n < |\bar{y}| \leq a\mu_n \\ \bar{y} & \text{if } |\bar{y}| > a\mu_n \end{cases}$$

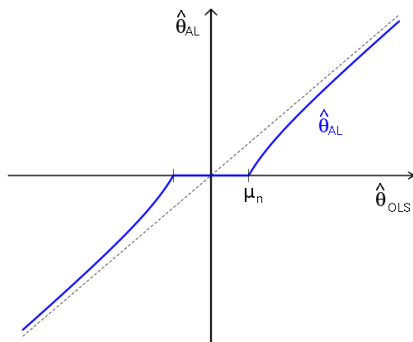


- Non-convex optimization problem.
- Possesses an “oracle-property” if sparsely-tuned.

Adaptive LASSO $\hat{\theta}_{AL}$

$$p(\theta) = 2n\mu_n^2|\theta|/|\bar{y}|$$

$$\hat{\theta}_{AL} = \begin{cases} 0 & \text{if } |\bar{y}| \leq \mu_n \\ \bar{y} - \mu_n^2/\bar{y} & \text{if } |\bar{y}| > \mu_n \end{cases}$$



- Equivalent to non-negative Garotte (Breiman, 1995)
- Possesses an “oracle-property” if sparsely-tuned.

Why moving-parameter asymptotics?

Let's you see what's really going on in large samples if the convergence is not uniform with respect the underlying parameter.

- The unpenalized LS estimator is $\hat{\theta}_{\text{OLS}} = \bar{y}$ in our model with $\hat{\theta}_{\text{OLS}} \sim N(\theta, 1/n)$, so that

$$n^{1/2}(\hat{\theta}_{\text{OLS}} - \theta) \sim N(0, 1)$$

for each sample size $n \in \mathbb{N}$, so the distribution is independent of θ .

- For $\hat{\theta}_{\text{AL}}$ (and other PLSEs), the distribution of $n^{1/2}(\hat{\theta}_{\text{AL}} - \theta)$ depends on θ in a complicated manner.

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$$\mathbf{1}(n^{1/2}\theta + x \geq 0) \Phi \left(-(n^{1/2}\theta - x)/2 + \sqrt{((n^{1/2}\theta + x)/2)^2 + n\mu_n^2} \right) \\ + \mathbf{1}(n^{1/2}\theta + x < 0) \Phi \left(-(n^{1/2}\theta - x)/2 - \sqrt{((n^{1/2}\theta + x)/2)^2 + n\mu_n^2} \right)$$

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- For $\hat{\theta}_{AL}$ (and other PLSEs), the distribution of $n^{1/2}(\hat{\theta}_{AL} - \theta)$ depends on θ in a complicated manner.
- Even for large n , the pointwise asymptotic distribution might be “far” from the finite-sample distribution of interest if the underlying convergence is not uniform, as we have seen yesterday.

Probability of choosing the **restricted model** M_R is given by

$$P_{n,\theta}(\hat{\theta} = 0) = \Phi(-n^{1/2}(\theta + \mu_n)) - \Phi(-n^{1/2}(\theta - \mu_n)),$$

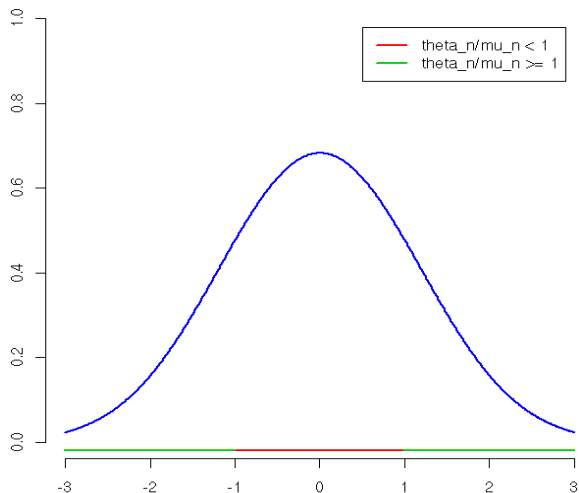
and clearly, the probability of choosing the **unrestricted model** M_U is

$$P_{n,\theta}(\hat{\theta} \neq 0) = 1 - P_{n,\theta}(\hat{\theta} = 0)$$

($\hat{\theta}$ any of the previous PLS estimators).

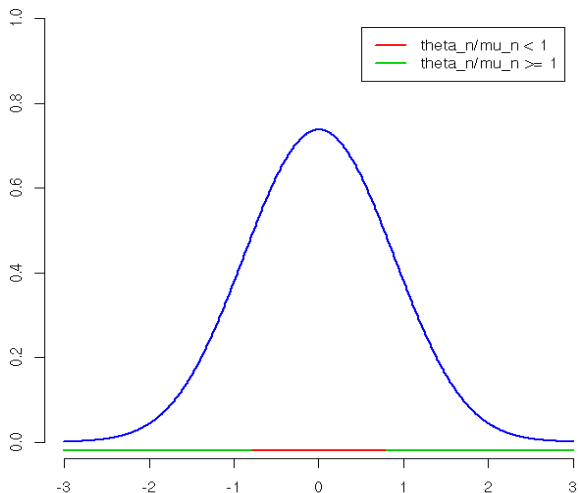
Asymptotic model selection probabilities

$$n = 1, \quad \mu_n = n^{-1/3} \text{ (consistent case)}$$



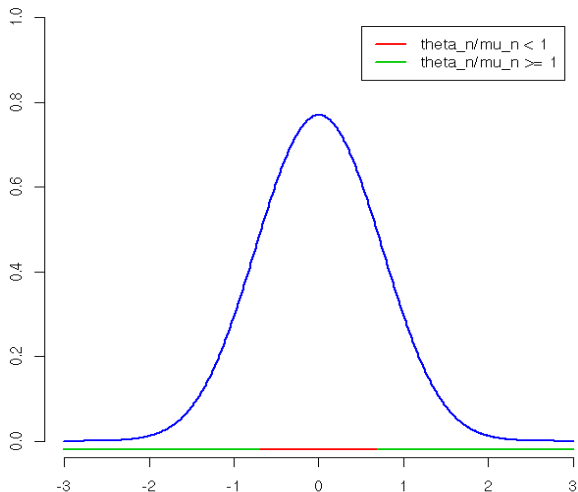
Asymptotic model selection probabilities

$$n = 2, \quad \mu_n = n^{-1/3} \text{ (consistent case)}$$



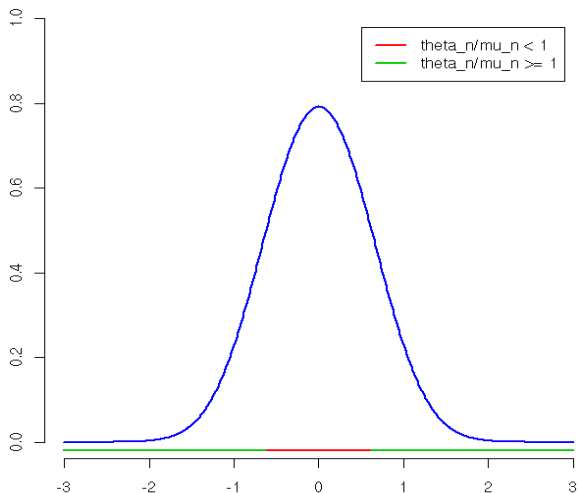
Asymptotic model selection probabilities

$$n = 3, \quad \mu_n = n^{-1/3} \text{ (consistent case)}$$



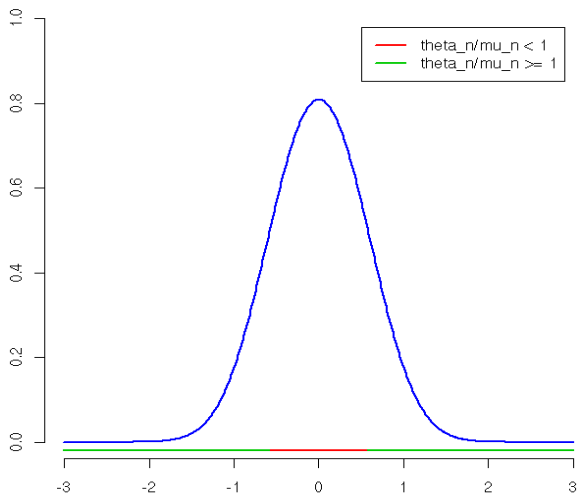
Asymptotic model selection probabilities

$$n = 4, \quad \mu_n = n^{-1/3} \text{ (consistent case)}$$



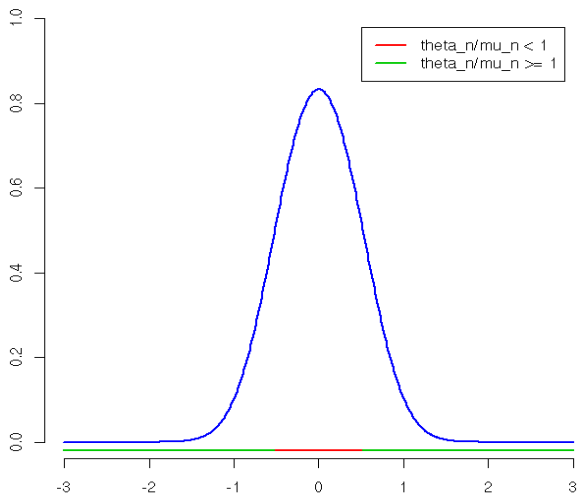
Asymptotic model selection probabilities

$$n = 5, \quad \mu_n = n^{-1/3} \text{ (consistent case)}$$



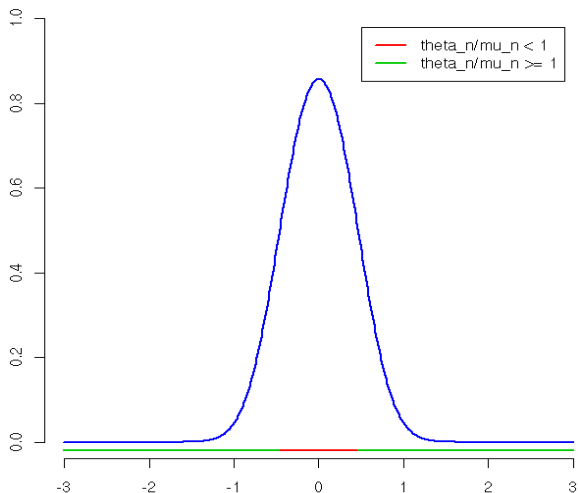
Asymptotic model selection probabilities

$$n = 7, \quad \mu_n = n^{-1/3} \text{ (consistent case)}$$



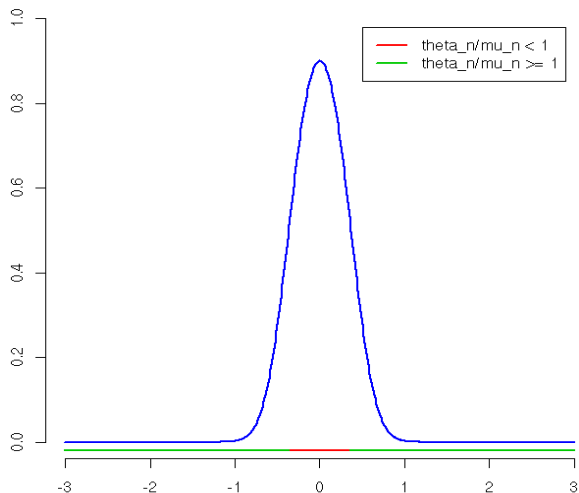
Asymptotic model selection probabilities

$n = 10$, $\mu_n = n^{-1/3}$ (consistent case)



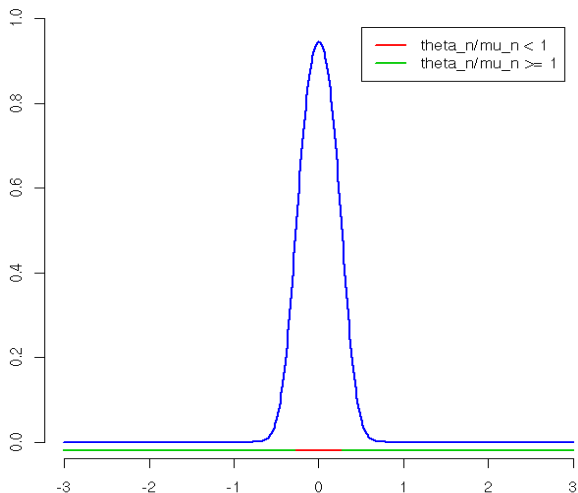
Asymptotic model selection probabilities

$n = 20$, $\mu_n = n^{-1/3}$ (consistent case)



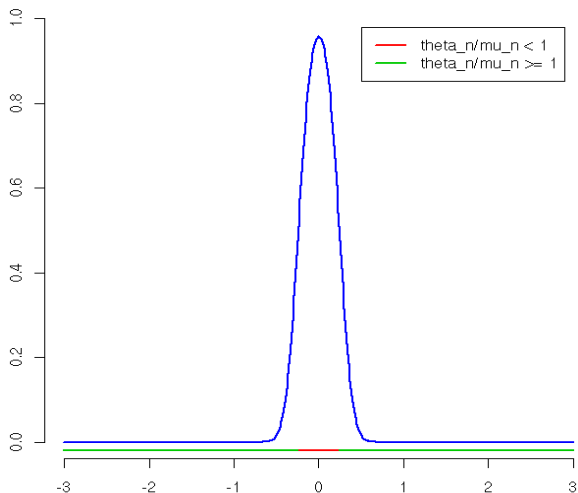
Asymptotic model selection probabilities

$n = 50$, $\mu_n = n^{-1/3}$ (consistent case)



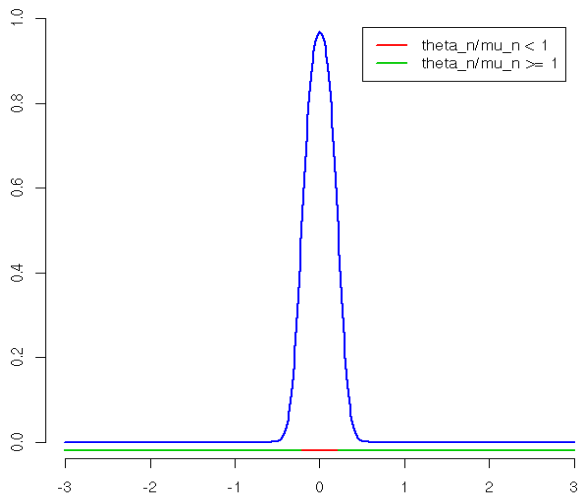
Asymptotic model selection probabilities

$n = 70$, $\mu_n = n^{-1/3}$ (consistent case)



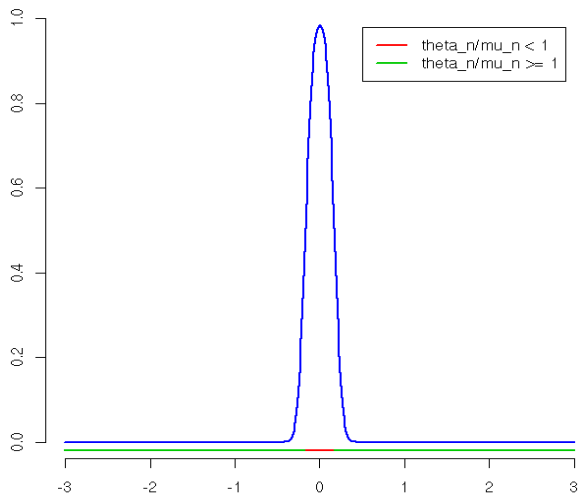
Asymptotic model selection probabilities

$n = 100$, $\mu_n = n^{-1/3}$ (consistent case)



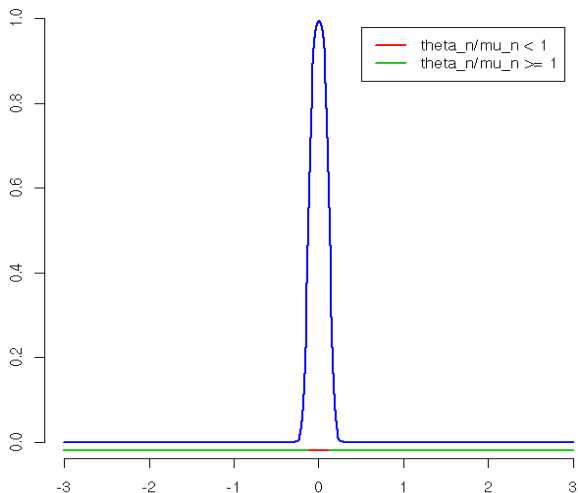
Asymptotic model selection probabilities

$n = 200$, $\mu_n = n^{-1/3}$ (consistent case)



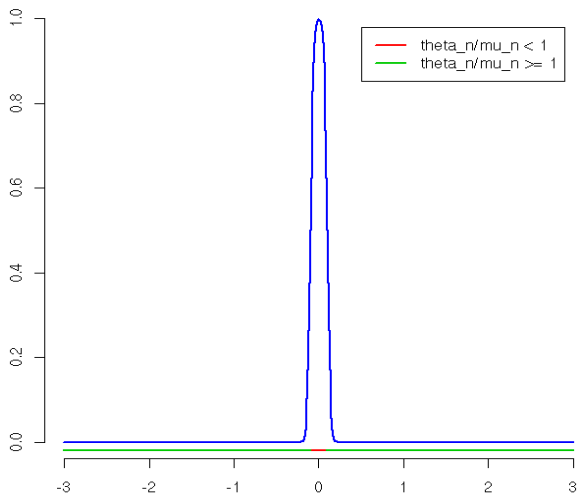
Asymptotic model selection probabilities

$n = 500$, $\mu_n = n^{-1/3}$ (consistent case)



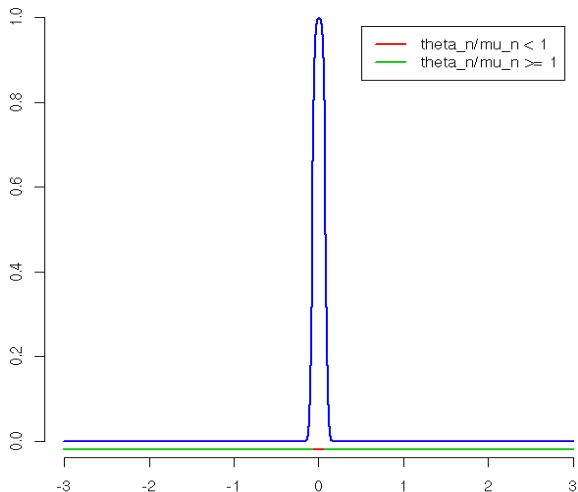
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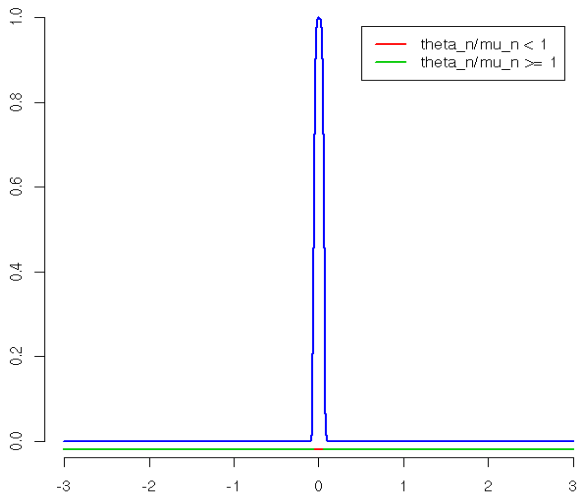
Asymptotic model selection probabilities

$n = 2000$, $\mu_n = n^{-1/3}$ (consistent case)



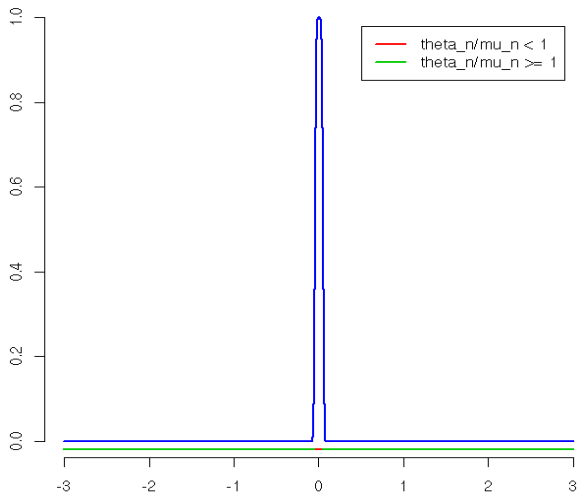
Asymptotic model selection probabilities

$n = 5000$, $\mu_n = n^{-1/3}$ (consistent case)



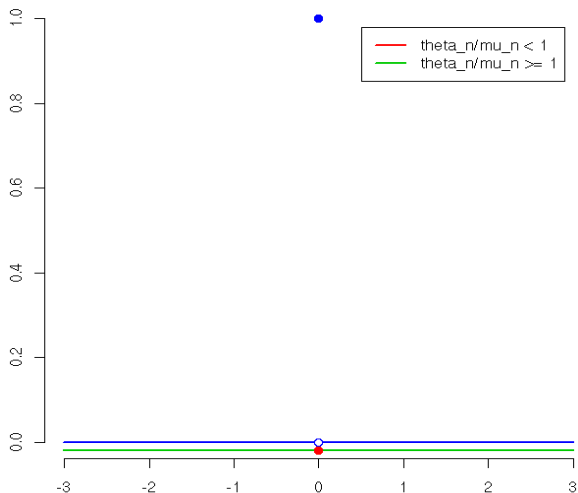
Asymptotic model selection probabilities

$n = 10000$, $\mu_n = n^{-1/3}$ (consistent case)



Asymptotic model selection probabilities

$$n = \infty, \quad \mu_n = n^{-1/3} \text{ (consistent case)}$$



Model selection probabilities

- ① **Consistent** case $(\mu_n \rightarrow 0, n^{1/2}\mu_n \rightarrow \infty)$

Assume $\theta_n/\mu_n \rightarrow \zeta \in \mathbb{R} \cup \{-\infty, \infty\}$. Then

$$\lim_{n \rightarrow \infty} P_{n, \theta_n}(\hat{\theta}_{\text{AL}} = 0) = \begin{cases} 1 & \text{if } |\zeta| < 1 \\ \Phi(r) & \text{if } |\zeta| = 1, n^{1/2}(\mu_n - \zeta\theta_n) \rightarrow r \in \mathbb{R} \cup \{-\infty, \infty\} \\ 0 & \text{if } |\zeta| > 1 \end{cases}$$

Deviations of θ_n from 0 of order $n^{-1/2}$ are not detected at all!

- ② **Conservative** case $(\mu_n \rightarrow 0, n^{1/2}\mu_n \rightarrow m, 0 \leq m < \infty)$

Assume $\theta_n \in \mathbb{R}$ satisfies $n^{1/2}\theta_n \rightarrow \nu \in \mathbb{R} \cup \{-\infty, \infty\}$. Then

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Deviations of θ_n from 0 of order $n^{-1/2}$ are detected with positive prob.

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- ② **Conservative** case $(\mu_n \rightarrow 0, n^{1/2}\mu_n \rightarrow m, 0 \leq m < \infty)$

Assume $\theta_n \in \mathbb{R}$ satisfies $n^{1/2}\theta_n \rightarrow \nu \in \mathbb{R} \cup \{-\infty, \infty\}$. Then

$$\lim_{n \rightarrow \infty} P_{n, \theta_n}(\hat{\theta}_{\text{AL}} = 0) = \Phi(-\nu + m) - \Phi(-\nu - m).$$

Deviations of θ_n from 0 of order $n^{-1/2}$ are detected with positive prob.

- Consistent procedures cannot uncover deviations from zero of order $n^{-1/2}$. This matters e.g. since usually $n^{1/2}(\hat{\theta} - \theta)$ is considered.
- Conservative procedures do detect such deviations with positive probability.
- Often the parameter space is assumed to be bounded away from zero by a rate smaller than $n^{-1/2}$.
- Model selection is “hard” when the true parameter θ is close to zero! (Yet this is an interesting case.)

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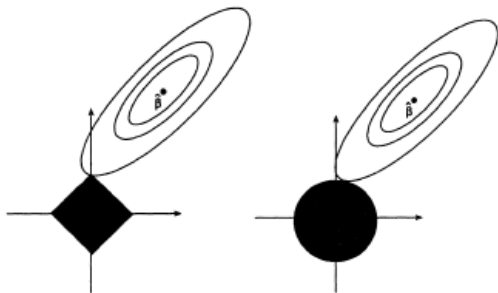
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(Plot from Tibshirani (1996))

Computational issues for (adaptive) LASSO

- Clearly, the LASSO estimator $\hat{\theta}_L$ depends on the tuning parameter λ_n .
- The “solution paths” for each component $\hat{\theta}_{L,i}(\lambda_n)$ can be shown to be **piecewise linear in λ_n** for each $i = 1, \dots, k$. (Rosset and Zhu, 2007)
- This property can be exploited to derive efficient algorithms to compute $\hat{\theta}_L$ “easily” **for all $\lambda_n \geq 0$** “at once”.
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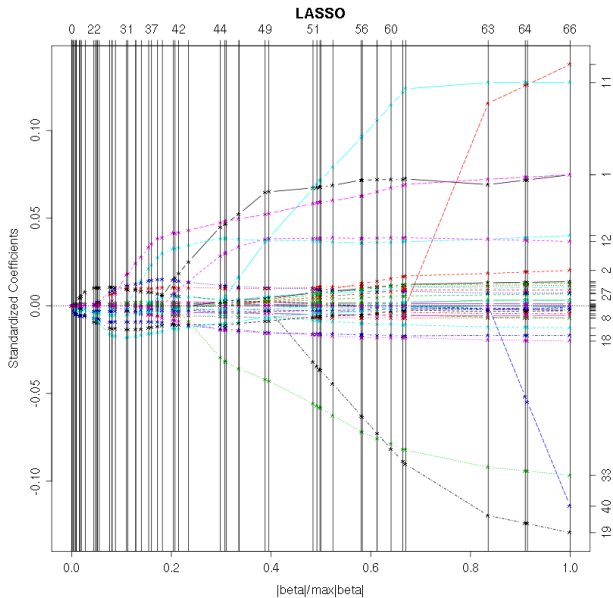
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Solution paths



Choosing the tuning parameter

λ_n is usually chosen after computing the solutions paths $\hat{\theta}_L(\lambda_n)$, most often by

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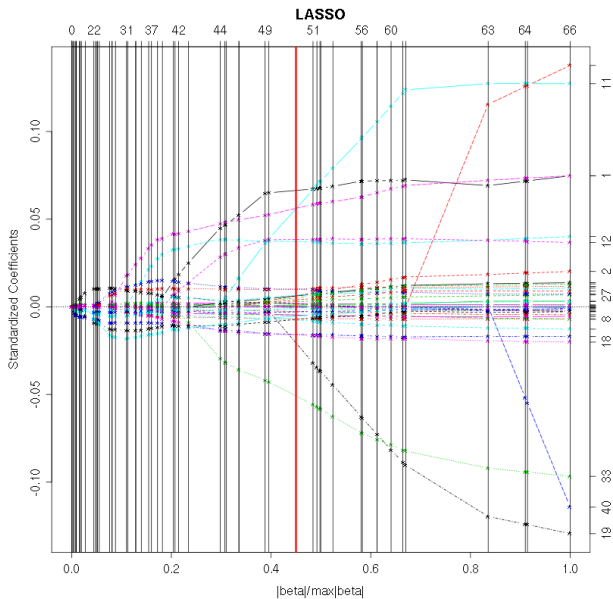
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