A nonparametric multi-state model for the analysis of human sleep

> Thomas Kneib & Andrea Hennerfeind Department of Statistics Ludwig-Maximilians-University Munich



6.7.2006

Human Sleep

- Human sleep can be considered a time-continuous stochastic process with discrete state space.
- Possible states:

AwakePhases of wakefulnessREMRapid eye movement phase (dream phase)Non-REMNon-REM phases (may be further differentiated)

- Aims of sleep research:
 - Describe the dynamics underlying the human sleep process.
 - Analyse associations between the sleep process and nocturnal hormonal secretion.
 - (Compare the sleep process of healthy and diseased persons.)

• Data generation:

- Sleep recording based on electroencephalographic (EEG) measures every 30 seconds (afterwards classified into the three sleep stages).
- Measurement of hormonal secretion based on blood samples taken every 10 minutes.
- A training night familiarises the participants of the study with the experimental environment.
- Available data:
 - 39 healthy "patients".
 - 21 male, 18 female.
 - Part of a larger study that investigates the impact of sleep withdrawal.



Multi-State Models

- Data structure similar to that of discrete Markov processes.
- Compact description of such a process in terms of transition intensities between the states.
- Simple parametric approaches are not appropriate in our application due to
 - Changing dynamics of human sleep over night.
 - Individual sleeping habits to be described by covariates.
 - A small number of available covariates (unobserved heterogeneity).
- \Rightarrow Model transition intensities nonparametrically.

A nonparametric multi-state model for the analysis of human sleep

• To reduce complexity, we consider a simplified transition space:



• Specification of the transition intensities:

$$\lambda_{AS,i}(t) = \exp \left[\gamma_0^{(AS)}(t) + s_i \beta^{(AS)} + b_i^{(AS)} \right]$$

$$\lambda_{SA,i}(t) = \exp \left[\gamma_0^{(SA)}(t) + s_i \beta^{(SA)} + b_i^{(SA)} \right]$$

$$\lambda_{NR,i}(t) = \exp \left[\gamma_0^{(NR)}(t) + c_i(t) \gamma_1^{(NR)}(t) + s_i \beta^{(NR)} + b_i^{(NR)} \right]$$

$$\lambda_{RN,i}(t) = \exp \left[\gamma_0^{(RN)}(t) + c_i(t) \gamma_1^{(RN)}(t) + s_i \beta^{(RN)} + b_i^{(RN)} \right]$$

where

$$\begin{array}{lll} c_i(t) & = & \begin{cases} 1 & \operatorname{cortisol} > 60 \ \mathrm{n} \ \mathrm{mol/l} \ \mathrm{at} \ \mathrm{time} \ t \\ 0 & \operatorname{cortisol} \le 60 \ \mathrm{n} \ \mathrm{mol/l} \ \mathrm{at} \ \mathrm{time} \ t , \\ s_i & = & \begin{cases} 1 & \operatorname{male} \\ 0 & \operatorname{female} , \end{cases} \\ b_i^{(j)} & = & \operatorname{transition-} \ \mathrm{and} \ \mathrm{individual-specific} \ \mathrm{frailty}. \end{array}$$

- Penalised splines for the baselines and time-varying effects:
 - Approximate $\gamma(t)$ by a weighted sum of B-spline basis functions

 $\gamma(t) = \sum_{j} \xi_j B_j(t).$

- Employ a large number of basis functions to enable flexibility.
- Penalise k-th order differences between parameters of adjacent basis functions to ensure smoothness:

$$Pen(\xi|\tau^2) = \frac{1}{2\tau^2} \sum_{j} (\Delta_k \xi_j)^2.$$

- Bayesian interpretation: Assume a k-th order random walk prior for ξ_j , e.g.

$$\xi_j = 2\xi_{j-1} - \xi_{j-2} + u_j, \quad u_j \sim N(0, \tau^2)$$
 (RW2).

- This yields the prior distribution:

$$p(\xi|\tau^2) \propto \exp\left(-\frac{1}{2\tau^2}\xi'K\xi\right).$$

• I.i.d. Gaussian priors for the frailty terms (with transition-specific variances):

 $b_i^{(j)} \sim N(0, \tau_j^2).$

Bayesian Inference

• The likelihood contribution for individual *i* can be constructed based on a counting process formulation of the model:

$$l_{i} = \sum_{h=1}^{k} \left[\int_{0}^{T_{i}} \log(\lambda_{hi}(t)) dN_{hi}(t) - \int_{0}^{T_{i}} \lambda_{hi}(t) Y_{hi}(t) dt \right]$$

=
$$\sum_{j=1}^{n_{i}} \sum_{h=1}^{k} \left[\delta_{hi}(t_{ij}) \log(\lambda_{hi}(t_{ij})) - Y_{hi}(t_{ij}) \int_{t_{i,j-1}}^{t_{ij}} \lambda_{hi}(t) dt \right].$$

- k number of possible transitions.
- $N_{hi}(t)$ counting process for type h event.
- $Y_{hi}(t)$ at risk indicator for type h event.
- t_{ij} event times of individual i.
- n_i number of events for individual i.
- $\delta_{hi}(t_{ij})$ transition indicator for type h transition.

• In principle, similar structure as in survival models with nonparametric hazard rate

 \Rightarrow Adopt methodology developed for nonparametric hazard regression.

- Fully Bayesian inference based on Markov Chain Monte Carlo simulation techniques (Hennerfeind, Brezger & Fahrmeir, 2006):
 - Assign inverse gamma priors to the variance and smoothing parameters.
 - Metropolis-Hastings update for the regression coefficients (based on IWLSproposals).
 - Gibbs sampler for the variances (inverse gamma with updated parameters).
 - Efficient algorithms make use of the sparse matrix structure of the matrices involved.

- Mixed model based empirical Bayes inference (Kneib & Fahrmeir, 2006):
 - Consider the variances and smoothing parameters as unknown constants to be estimated by mixed model methodology.
 - Problem: The P-spline priors are partially improper.
 - Mixed model representation: Decompose the vector of regression coefficients as

$$\xi = X\beta + Zb,$$

where

 $p(\beta) \propto const$ and $b \sim N(0, \tau^2 I)$.

 $\Rightarrow \beta$ is a fixed effect and b is an i.i.d. random effect.

- Penalised likelihood estimation of the regression coefficients in the mixed model (posterior modes).
- Marginal likelihood estimation of the variance and smoothing parameters.

Results

• Baseline effects:



• Time-varying effects for a high level of cortisol:



- Gender differences for all the transitions (mostly increased for males).
- Only the fully Bayesian approach identifies individual-specific variation.

Software

- Multi-state models will be part of the next release of BayesX.
- Public domain software package for Bayesian inference in geoadditive and related models.



• Available from

http://www.stat.uni-muenchen.de/~bayesx

Discussion

- Computationally feasible nonparametric approach for the analysis of multi-state models.
- Fully Bayesian and empirical Bayes inference.
- Directly extendable to more complicated models including
 - Nonparametric effects of continuous covariates.
 - Spatial effects.
 - Interaction surfaces and varying coefficients.
- Future work:
 - Application to larger data sets and different types of multi-state models.
 - Consider coarsened observations, i.e. interval censored multi-state data.

References

- BREZGER, KNEIB & LANG (2005). BayesX: Analyzing Bayesian structured additive regression models. *Journal of Statistical Software*, **14** (11).
- HENNERFEIND, BREZGER, AND FAHRMEIR (2006): Geoadditive Survival Models. Journal of the American Statistical Association, to appear.
- KNEIB & FAHRMEIR (2006): A mixed model approach for geoadditive hazard regression. *Scandinavian Journal of Statistics*, to appear.
- A place called home:

http://www.stat.uni-muenchen.de/~kneib