# Model Choice and Variable Selection in Geoadditive Regression Models

Thomas Kneib

### Department of Statistics Ludwig-Maximilians-University Munich

joint work with

Torsten Hothorn

Gerhard Tutz



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### **Geoadditive Regression: Forest Health Example**

- Aim of the study: Identify factors influencing the health status of trees.
- Database: Yearly visual forest health inventories carried out from 1983 to 2004 in a northern Bavarian forest district.
- 83 observation plots of beeches within a 15 km times 10 km area.
- Response: binary defoliation indicator  $y_{it}$  of plot i in year t (1 = defoliation higher than 25%).
- Spatially structured longitudinal data.



#### • Covariates:

Continuous:	average age of trees at the observation plot elevation above sea level in meters inclination of slope in percent depth of soil layer in centimeters pH-value in 0 – 2cm depth density of forest canopy in percent
Categorical	thickness of humus layer in 5 ordered categories level of soil moisture base saturation in 4 ordered categories
Binary	type of stand application of fertilisation

• Possible model:

$$P(y_{it} = 1) = \frac{\exp(\eta_{it})}{1 + \exp(\eta_{it})}$$

where  $\eta_{it}$  is a geoadditive predictor of the form

$$\begin{array}{lll} \eta_{it} &=& f_1(\mathsf{age}_{it},t) + & \text{interaction between age and calendar time.} \\ & f_2(\mathsf{canopy}_{it}) + & \mathsf{smooth effects of the canopy density and} \\ & f_3(\mathsf{soil}_{it}) + & \text{the depth of the soil layer.} \\ & f_{\mathsf{spat}}(s_{ix},s_{iy}) + & \mathsf{structured and} \\ & b_i + & \text{unstructured spatial random effects.} \\ & x'_{it}\beta & & \text{parametric effects of type of stand, fertilisation,} \\ & \text{thickness of humus layer, level of soil moisture} \\ & \text{and base saturation.} \end{array}$$





- Questions:
  - How do we estimate the model?  $\Rightarrow$  Inference.
  - How do we come up with the model specification?  $\Rightarrow$  Model choice and variable selection.

### $\Rightarrow$ Componentwise boosting for geoadditive regression models.

### **Base-Learners For Geoadditive Regression Models**

• Componentwise base-learning procedures for geoadditive regression models can be derived from univariate Gaussian smoothing approaches such as

$y = g(x) + \varepsilon$	smooth nonparametric effect
$y = g(x_1, x_2) + \varepsilon$	smooth surface / spatial effect
$y = x_1 g(x_2) + \varepsilon$	varying coefficients

where  $\varepsilon \sim N(0, \sigma^2 I)$ .

• All base-learners will be given by penalised least squares (PLS) fits

$$\hat{y} = X(X'X + \lambda K)^{-1}X'y$$

characterised by the hat matrix

$$S_{\lambda} = X(X'X + \lambda K)^{-1}X'.$$

• Recall univariate penalised spline smoothing: Approximate g(x) by a linear combination of B-spline basis functions, i.e.

$$g(x) = \sum_{j} \beta_{j} B_{j}(x)$$

and define a difference penalty

pen(
$$\beta$$
) =  $\lambda \sum_{j} (\beta_j - \beta_{j-1})^2$  or pen( $\beta$ ) =  $\lambda \sum_{j} (\beta_j - 2\beta_{j-1} + \beta_{j-2})^2$ .

to ensure smoothness.

• Model and penalty in matrix notation:

$$y = X\beta + \varepsilon$$
 and  $pen(\beta) = \lambda \beta' K \beta$ .

• Penalised least squares estimate and fit:

$$\hat{\beta} = (X'X + \lambda K)^{-1}X'y \qquad \hat{y} = X(X'X + \lambda K)^{-1}X'y.$$

• PLS base-learner for interaction surfaces and spatial effects  $f(x_1, x_2)$ :



• Define bivariate Tensor product basis functions

$$B_{jk}(x_1, x_2) = B_j(x_1)B_k(x_2).$$

• Based on penalty matrices  $K_1$  and  $K_2$  for univariate fits define an overall penalty as

$$\operatorname{pen}(\beta) = \lambda \beta' \underbrace{(I \otimes K_1 + K_2 \otimes I)}_{=K} \beta.$$

• PLS base-learner for varying coefficient terms

$$y = x_1 g(x_2) + \varepsilon$$

Representing  $g(x_2)$  as a penalised spline yields  $y = X\beta + \varepsilon$ , where

$$X = \operatorname{diag}(x_{11}, \dots, x_{n1})X^*$$

and  $X^*$  is the design matrix corresponding to  $g(x_2)$ .

- PLS base-learners can also be defined for
  - Random intercepts and random slopes,
  - Space-varying effects.

# **Complexity Adjustment**

- The flexibility of penalised least squares base-learners depends on the choice of the smoothing parameter.
- Typical strategy: fix the smoothing parameter at a large pre-specified value.
- Difficult when comparing fixed effects, nonparametric effects and spatial effects.

 $\Rightarrow$  More flexible base-learners will be preferred in the boosting iterations leading to potential selection and estimation bias.

- We need an intuitive measure of complexity.
- Effective degrees of freedom of a penalised least-squares base-learner:

$$df(\lambda) = trace(X(X'X + \lambda K)^{-1}X').$$

• Choose the smoothing parameters for the base-learners such that

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df(\lambda) = 1.
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• Can not be achieved for most base-learners since

 $\lim_{\lambda \to \infty} \mathrm{df}(\lambda) \geq 1.$ 

- For example, a polynomial of order k-1 remains unpenalised for penalised splines with k-th order difference penalty.
- A reparameterisation has to be applied, leading for example to

$$f(x) = \beta_0 + \beta_1 x + \ldots + \beta_{k-1} x^{k-1} + f_{\text{centered}}(x).$$

• Assign separate base-learners to the parametric components and a one degree of freedom PLS base-learner to the centered effect.

## **Boosting Geoadditive Regression Models**

• Generic representation of geoadditive models:

$$\eta(\cdot) = \beta_0 + \sum_{j=1}^r f_j(\cdot)$$

where the functions  $f_j(\cdot)$  represent the candidate functions of the predictor.

- Each candidate function is associated with a PLS base-learner.
- Early stopping of the boosting algorithm implements variables selection.
- Defining concurring base-learners implements model choice (for example linear vs. nonlinear modelling).
- The number of boosting iterations can be determined based on AIC reduction or cross-validation.

# Habitat Suitability Analyses

- Identify factors influencing habitat suitability for breeding bird communities collected in seven structural guilds (SG).
- Variable of interest: Counts of subjects from a specific structural guild collected at 258 observation plots in a Northern Bavarian forest district.
- Research questions:
  - a) Which covariates influence habitat suitability (31 covariates in total)? Does spatial correlation have an impact on variable selection?
  - b) Are there nonlinear effects of some of the covariates?
  - c) Are effects varying spatially?
- All questions can be addressed with the boosting approach (but we focus on a)).

• Selection frequencies in a spatial Poisson-GLM:

	GST	DBH	AOT	AFS	DWC	LOG	SNA	COO
non-spatial GLM	0	0	0	0.06	0.3	0	0.01	0
spatial with 5 df	0	0.02	0	0.01	0.05	0	0.01	0
spatial with 1 df	0	0	0	0.06	0.15	0	0	0
	СОМ	CRS	HRS	OAK	СОТ	PIO	ALA	MAT
non-spatial GLM	0.03	0.04	0.03	0.05	0.06	0	0.04	0.06
spatial with 5 df	0	0.01	0	0	0	0	0.01	0.05
spatial with 1 df	0.03	0.02	0.02	0.04	0.05	0	0.03	0.04
	GAP	AGR	ROA	LCA	SCA	HOT	CTR	RLL
non-spatial GLM	0.03	0	0	0.1	0.07	0	0	0
spatial with 5 df	0.01	0	0.01	0.01	0.01	0	0	0
spatial with 1 df	0.03	0	0	0.07	0.06	0	0	0
	BOL	MSP	MDT	MAD	COL	AGL	SUL	spatial
non-spatial GLM	0	0.06	0	0	0.05	0	0	0
spatial with 5 df	0	0	0	0	0.03	0	0	0.76
spatial with 1 df	0	0.04	0	0	0.04	0	0	0.3

• A similar picture is obtained from considering the estimated regression coefficients.

• Spatial effects for high and low degrees of freedom:



- Spatial correlation has non-negligible influence on variable selection.
- Making terms comparable in terms of complexity is essential to obtain valid results.

# **Summary & Extensions**

- Generic boosting algorithm for model choice and variable selection in geoadditive regression models.
- Avoid selection bias by careful parameterisation.
- Implemented in the R-package **mboost**.
- Future plans:
  - Derive base-learning procedures for other types of spatial effects (regional data, anisotropic spatial effects).
  - Construct spatio-temporal base-learners based on tensor product approaches.

- Reference: Kneib, T., Hothorn, T. and Tutz, G.: Model Choice and Variable Selection in Geoadditive Regression. Under revision for *Biometrics*.
- Find out more:

http://www.stat.uni-muenchen.de/~kneib