



Smoothing parameter selection in two frameworks for spline estimators

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Model

Nonparametric model for n data pairs (y_i, x_i)

$$Y_i = f(x_i) + \epsilon_i, \quad i = 1, \dots, n, \quad \epsilon_i \sim \mathcal{N}(0, \sigma^2),$$

for fixed $x_i \in [0, 1]$ and an unknown smooth f

Smoothing parameter λ for any $\hat{f}(x) = \hat{f}(x; \lambda)$ can be chosen to minimize some unbiased estimator of the mean square risk

$$R(\hat{f}, f) = \mathbb{E} \left[\frac{1}{n} \sum_{i=1}^n \left\{ \hat{f}(x_i; \lambda) - f(x_i) \right\}^2 \right]$$



Choice of λ

In practice GCV (or asymptotic equivalent AIC, C_p) as \hat{R} is used

$$E \{ \text{GCV}(\lambda) \} = R(\hat{f}, f) \{ 1 + o(1) \} + \sigma^2 \{ 1 + o(n^{-1}) \}$$

Known practical problems of GCV and similar criteria

- large variability of $\hat{\lambda}$ obtained with GCV
- extremely sensitive to serial dependences in ϵ_j
- unstable in low signal-to-noise ratio situations



Two frameworks for splines

Frequentist model

$$Y_i = f(x_i) + \epsilon_i = \sum_{j=0}^{q-1} \beta_j x_i^j + \int_0^1 f^{(q)}(t) \frac{(x-t)_+^{q-1}}{(q-1)!} dt + \epsilon_i,$$

for $x_i \in [0, 1]$, $f \in \mathcal{W}^q[0, 1]$, $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$

Stochastic model

$$Y_i = F(x_i) + \epsilon_i = \sum_{j=0}^{q-1} \beta_j x_i^j + \sigma_u \int_0^1 \frac{(x_i - t)_+^{q-1}}{(q-1)!} dW(t) + \epsilon_i,$$

for $x_+ = \max\{0, x\}$, $W(t)$ standard Wiener process and $i = 1, \dots, n$



Two frameworks

In the frequentist framework f is estimated from

$$\min_{f \in \mathcal{W}^q[0,1]} \left[\frac{1}{n} \sum_{i=1}^n \{y_i - f(x_i)\}^2 + \lambda \int_0^1 \{f(x)^{(q)}\}^2 dx \right],$$

which is minimized by the smoothing spline estimator \hat{f}

In the stochastic framework F is found as the best linear unbiased predictor, which equals to \hat{f} with $\lambda = \sigma^2/(n\sigma_u^2)$

Note that the sample paths of $F \notin \mathcal{W}^q[0,1]$ with probability 1 (are less smooth)



Low-rank splines

Let $\mathcal{S}(2q-1, k)$ be a spline space of degree $2q-1$ based on k knots τ_j

Making further assumptions on regularity of x_i and τ_j and on

$$k = \text{const } n^\nu, \nu \in (1/(2q), 1), \lambda \rightarrow 0, \lambda n \rightarrow \infty$$

one solves a lower dimensional problem ($k < n$) to estimate $f \in \mathcal{W}^q$

$$\min_{s \in \mathcal{S}(2q-1, k)} \left[\frac{1}{n} \sum_{i=1}^n \{y_i - s(x_i)\}^2 + \lambda \int_0^1 \{s^{(q)}(x)\}^2 dx \right]$$

Similarly, the estimator in the stochastic framework is generalized



Two smoothing parameters

Estimators in both models are equal up to the smoothing parameter

Smoothing parameter λ

- relies on the frequentist model with $f \in \mathcal{W}^q[0, 1]$
- estimated by minimizing criteria that estimate $R(\hat{f}, f)$

Smoothing parameter σ^2/σ_u^2

- relies on the stochastic model
- estimated by maximizing the corresponding likelihood



Frequentist model

Aim to answer

How both smoothing parameter estimators behave
if the data follow a frequentist model?

Available results

- Sun & Speckman (2000, unpublished) asymptotic distribution of the estimators (smoothing splines) for functions satisfying natural boundary conditions



Oracle smoothing parameters

Let denote

$$\lambda_f = \lambda_f(n) = \arg \min_{\lambda > 0} E\{\text{GCV}(\lambda)\} = \arg \min_{\lambda > 0} R(\hat{f}, f)\{1 + o(1)\}$$

and

$$\lambda_r = \lambda_r(n) = \arg \min_{\sigma^2/\sigma_u^2 > 0} E_f\{-l_p(\sigma^2/\sigma_u^2; y)\}$$

with l_p as the profile (restricted) likelihood for σ^2/σ_u^2

λ_r is the smoothing parameter that one gets in the mean from the likelihood in case the data follow $Y_i = f(x_i) + \epsilon_i$, $f \in \mathcal{W}^q$



Oracle smoothing parameters

Let $f \in \mathcal{W}^{qm}[0, 1]$, $m \in [1, 2]$, where \mathcal{W}^{qm} is a fractional order Sobolev (Besov) space with certain boundary conditions

$$\lambda_f \geq C(f, q, m, \sigma^2) n^{-\frac{2q}{2qm+1}}, \quad m \in [1, 2],$$

$$\lambda_r = C(f, q, \sigma^2) n^{-\frac{2q}{2q+1}}, \quad \forall m$$

as shown in Wahba (1995, AoS)

- λ_f adapts to the unknown smoothness and boundary conditions (up to $2q$)
- performance of λ_r depends on n , q and $C(f, q, \sigma^2)$



Oracle smoothing parameters

It follows, that λ_r is suboptimal

- $\lambda_f/\lambda_r \rightarrow \infty$ with $n \rightarrow \infty$ for $f \in \mathcal{W}^{qm}[0, 1]$, $m \in (1, 2]$
- $\hat{f}(\lambda_r)$ (asymptotically) undersmooths f compared to $\hat{f}(\lambda_f)$

In many small-samples simulation studies (e.g. Kohn, JASA, 1991) $\hat{\sigma}^2/\hat{\sigma}_u^2$ appeared to perform better than $\hat{\lambda}$

\hookrightarrow look at the properties of estimators $\hat{\sigma}^2/\hat{\sigma}_u^2$ and $\hat{\lambda}$



Smoothing parameter estimators

Under the frequentist model and mentioned assumptions on x_i , τ_i , k , λ

$$\frac{\hat{\sigma}^2/\hat{\sigma}_u^2}{\lambda_r} \xrightarrow{\mathcal{P}} 1 \quad \text{and} \quad \frac{\hat{\lambda}}{\lambda_f} \xrightarrow{\mathcal{P}} 1.$$

Moreover,

$$\lambda_r^{-1/(4q)} \left(\frac{\hat{\sigma}^2/\hat{\sigma}_u^2}{\lambda_r} - 1 \right) \xrightarrow{\mathcal{D}} \mathcal{N}(0, 2C_1(q))$$

and

$$\lambda_f^{-1/(4q)} \left(\frac{\hat{\lambda}}{\lambda_f} - 1 \right) \xrightarrow{\mathcal{D}} \mathcal{N}(0, 2C_2(q)),$$



Smoothing parameter estimators

$$C_1(q) = c_\rho \operatorname{sinc}\{\pi/(2q)\} \frac{q}{12q^2 - 3}$$

$$C_2(q) = c_\rho \operatorname{sinc}\{\pi/(2q)\} \frac{q(12q^2 + 8q + 1)}{15(8q^2 - 2q - 1)}$$

- c_ρ depends on the design density ρ
- $C_1(q)$ decreases with q
- $C_2(q)$ increases with q
- $C_2(q)/C_1(q)$ grows fast with q



Smoothing parameter estimators

$$\begin{aligned}\text{var} \left(\frac{\hat{\lambda}}{\lambda_f} \right) &= O \left(n^{-\frac{1}{2qm+1}} \right), \quad m \in [1, 2] \\ \text{var} \left(\frac{\hat{\sigma}^2 / \hat{\sigma}_u^2}{\lambda_r} \right) &= O \left(n^{-\frac{1}{2q+1}} \right)\end{aligned}$$

- the convergence rate of $\hat{\lambda}/\lambda_f$ and $\hat{\sigma}^2/(\lambda_r \hat{\sigma}_u^2)$ to 1 is very slow
- $\hat{\lambda}/\lambda_f$ converge more slowly for smoother functions



Smoothing parameter estimators

$$\frac{\text{var}(\hat{\lambda})}{\text{var}(\hat{\sigma}^2/\hat{\sigma}_u^2)} \approx q(q+2) \left(\frac{\lambda_f}{\lambda_r} \right)^{2+1/(2q)}$$

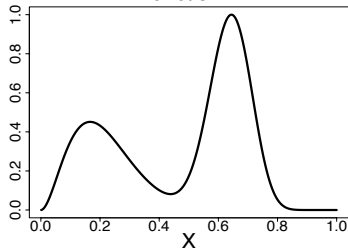
That is due to $\lambda_f/\lambda_r \rightarrow \infty$, $n \rightarrow \infty$

- $\text{var}(\hat{\lambda}_f)/\text{var}(\hat{\sigma}^2/\hat{\sigma}_u^2)$ is large and grows with q and n
- $\hat{f}(\hat{\sigma}^2/\hat{\sigma}_u^2)$ is much more stable than $\hat{f}(\hat{\lambda}_f)$

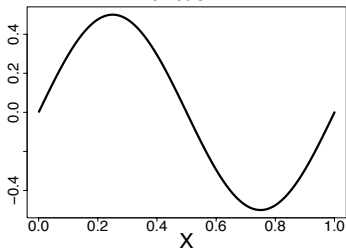


Simulations $q = 2$

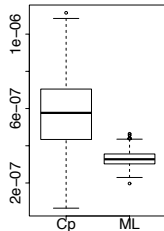
Function 1



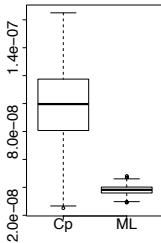
Function 2



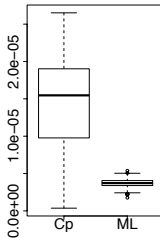
n=350



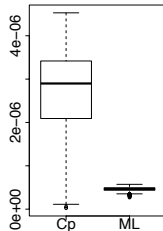
n=1000



n=350



n=1000





Simulations

Simulation results show

- $\hat{\lambda}$ is much more variable than $\hat{\sigma}^2/\hat{\sigma}_u^2$
- $\lambda_f/\lambda_r > 1$ and grows with n
- for a periodic f_2 , λ_f/λ_r is larger than for f_1
- in small samples $\hat{f}(\hat{\lambda})$, $\hat{f}(\hat{\sigma}^2/\hat{\sigma}_u^2)$ perform comparable for f_1

	$n = 350$		$n = 1000$	
	f_1	f_2	f_1	f_2
$\frac{R(\hat{f}(\hat{\lambda}), f)}{R(\hat{f}(\hat{\sigma}^2/\hat{\sigma}_u^2), f)}$	1.02	0.99	0.90	0.80



Data-driven q

Large ratio λ_f/λ_r suggests that f is smoother than assumed $\mathcal{W}^q[0, 1]$

If q can be chosen data-driven, such that $\lambda_f/\lambda_r \approx 1$ for given n and f , then $\hat{\sigma}^2/\hat{\sigma}_u^2$ should outperform $\hat{\lambda}$ due to much smaller variance

One possible way is to choose q such that

$$R(q) = |Y^t(I_n - S)S^2Y - \hat{\sigma}^2\{\text{tr}(S^2) - q\}|$$

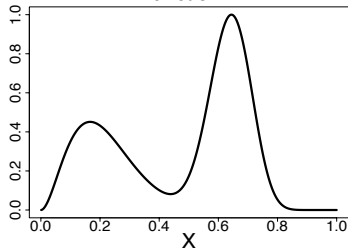
is smallest; here $S = S(\hat{\sigma}^2/\hat{\sigma}_u^2)$ is the smoother matrix

This criterion is obtained comparing estimating equations of both smoothing parameters

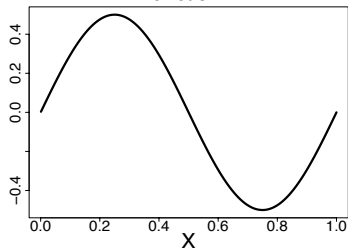


Simulations $n = 1000$

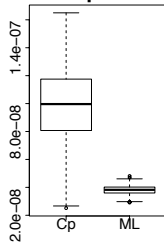
Function 1



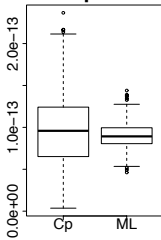
Function 2



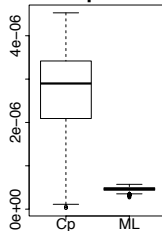
$q=2$



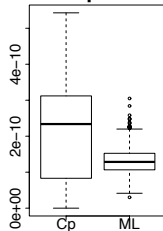
$q=4$



$q=2$



$q=4$





Conclusion

- λ_f/λ_r grows with n
- λ_f is able to adapt to the unknown smoothness (up to $2q$)
- performance of λ_r depends on n and q

- $\hat{\lambda}$ and $\hat{\sigma}^2/\hat{\sigma}_u^2$ are both consistent and asymptotically normal
- convergence rate of $\hat{\lambda}$ and $\hat{\sigma}^2/\hat{\sigma}_u^2$ is very slow
- $\hat{\lambda}$ converges to λ slower for smoother functions
- constants in asymptotic variances of $\hat{\lambda}$ and $\hat{\sigma}^2/\hat{\sigma}_u^2$ are obtained

- taking a larger q can improve the performance of $\hat{\sigma}^2/\hat{\sigma}_u^2$
- data-driven choice of q is interesting direction for further research