



# Smoothing parameter selection in two frameworks for spline estimators

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## Model

Nonparametric model for  $n$  data pairs  $(y_i, x_i)$

$$Y_i = f(x_i) + \epsilon_i, \quad i = 1, \dots, n, \quad \epsilon_i \sim \mathcal{N}(0, \sigma^2),$$

for fixed  $x_i \in [0, 1]$  and an unknown smooth  $f$

Smoothing parameter  $\lambda$  for any  $\hat{f}(x) = \hat{f}(x; \lambda)$  can be chosen to minimize some unbiased estimator of the mean square risk

$$R(\hat{f}, f) = \mathbb{E} \left[ \frac{1}{n} \sum_{i=1}^n \left\{ \hat{f}(x_i; \lambda) - f(x_i) \right\}^2 \right]$$



## Choice of $\lambda$

In practice GCV (or asymptotic equivalent AIC,  $C_p$ ) as  $\hat{R}$  is used

$$E \{ \text{GCV}(\lambda) \} = R(\hat{f}, f) \{ 1 + o(1) \} + \sigma^2 \{ 1 + o(n^{-1}) \}$$

Known practical problems of GCV and similar criteria

- large variability of  $\hat{\lambda}$  obtained with GCV
- extremely sensitive to serial dependences in  $\epsilon_j$
- unstable in low signal-to-noise ratio situations



## Two frameworks for splines

### Frequentist model

$$Y_i = f(x_i) + \epsilon_i = \sum_{j=0}^{q-1} \beta_j x_i^j + \int_0^1 f^{(q)}(t) \frac{(x-t)_+^{q-1}}{(q-1)!} dt + \epsilon_i,$$

for  $x_i \in [0, 1]$ ,  $f \in \mathcal{W}^q[0, 1]$ ,  $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$

### Stochastic model

$$Y_i = F(x_i) + \epsilon_i = \sum_{j=0}^{q-1} \beta_j x_i^j + \sigma_u \int_0^1 \frac{(x_i - t)_+^{q-1}}{(q-1)!} dW(t) + \epsilon_i,$$

for  $x_+ = \max\{0, x\}$ ,  $W(t)$  standard Wiener process and  $i = 1, \dots, n$



## Two frameworks

In the frequentist framework  $f$  is estimated from

$$\min_{f \in \mathcal{W}^q[0,1]} \left[ \frac{1}{n} \sum_{i=1}^n \{y_i - f(x_i)\}^2 + \lambda \int_0^1 \{f(x)^{(q)}\}^2 dx \right],$$

which is minimized by the smoothing spline estimator  $\hat{f}$

In the stochastic framework  $F$  is found as the best linear unbiased predictor, which equals to  $\hat{f}$  with  $\lambda = \sigma^2 / (n\sigma_u^2)$

Note that the sample paths of  $F \notin \mathcal{W}^q[0,1]$  with probability 1 (are less smooth)



## Low-rank splines

Let  $\mathcal{S}(2q-1, k)$  be a spline space of degree  $2q-1$  based on  $k$  knots  $\tau_j$

Making further assumptions on regularity of  $x_i$  and  $\tau_j$  and on

$$k = \text{const } n^\nu, \nu \in (1/(2q), 1), \lambda \rightarrow 0, \lambda n \rightarrow \infty$$

one solves a lower dimensional problem ( $k < n$ ) to estimate  $f \in \mathcal{W}^q$

$$\min_{s \in \mathcal{S}(2q-1, k)} \left[ \frac{1}{n} \sum_{i=1}^n \{y_i - s(x_i)\}^2 + \lambda \int_0^1 \{s^{(q)}(x)\}^2 dx \right]$$

Similarly, the estimator in the stochastic framework is generalized



## Two smoothing parameters

Estimators in both models are equal up to the smoothing parameter

Smoothing parameter  $\lambda$

- relies on the frequentist model with  $f \in \mathcal{W}^q[0, 1]$
- estimated by minimizing criteria that estimate  $R(\hat{f}, f)$

Smoothing parameter  $\sigma^2/\sigma_u^2$

- relies on the stochastic model
- estimated by maximizing the corresponding likelihood



## Frequentist model

Aim to answer

How both smoothing parameter estimators behave  
if the data follow a frequentist model?

Available results

- Sun & Speckman (2000, unpublished) asymptotic distribution of the estimators (smoothing splines) for functions satisfying natural boundary conditions



## Oracle smoothing parameters

Let denote

$$\lambda_f = \lambda_f(n) = \arg \min_{\lambda > 0} E\{\text{GCV}(\lambda)\} = \arg \min_{\lambda > 0} R(\hat{f}, f)\{1 + o(1)\}$$

and

$$\lambda_r = \lambda_r(n) = \arg \min_{\sigma^2/\sigma_u^2 > 0} E_f\{-l_p(\sigma^2/\sigma_u^2; y)\}$$

with  $l_p$  as the profile (restricted) likelihood for  $\sigma^2/\sigma_u^2$

$\lambda_r$  is the smoothing parameter that one gets in the mean from the likelihood in case the data follow  $Y_i = f(x_i) + \epsilon_i$ ,  $f \in \mathcal{W}^q$



## Oracle smoothing parameters

Let  $f \in \mathcal{W}^{qm}[0, 1]$ ,  $m \in [1, 2]$ , where  $\mathcal{W}^{qm}$  is a fractional order Sobolev (Besov) space with certain boundary conditions

$$\lambda_f \geq C(f, q, m, \sigma^2) n^{-\frac{2q}{2qm+1}}, m \in [1, 2],$$

$$\lambda_r = C(f, q, \sigma^2) n^{-\frac{2q}{2q+1}}, \forall m$$

as shown in Wahba (1995, AoS)

- $\lambda_f$  adapts to the unknown smoothness and boundary conditions (up to  $2q$ )
- performance of  $\lambda_r$  depends on  $n$ ,  $q$  and  $C(f, q, \sigma^2)$



## Oracle smoothing parameters

It follows, that  $\lambda_r$  is suboptimal

- $\lambda_f/\lambda_r \rightarrow \infty$  with  $n \rightarrow \infty$  for  $f \in \mathcal{W}^{qm}[0, 1]$ ,  $m \in (1, 2]$
- $\hat{f}(\lambda_r)$  (asymptotically) undersmooths  $f$  compared to  $\hat{f}(\lambda_f)$

In many small-samples simulation studies (e.g. Kohn, JASA, 1991)  $\hat{\sigma}^2/\hat{\sigma}_u^2$  appeared to perform better than  $\hat{\lambda}$

$\Leftrightarrow$  look at the properties of estimators  $\hat{\sigma}^2/\hat{\sigma}_u^2$  and  $\hat{\lambda}$



## Smoothing parameter estimators

Under the frequentist model and mentioned assumptions on  $x_i$ ,  $\tau_i$ ,  $k$ ,  $\lambda$

$$\frac{\widehat{\sigma}^2 / \widehat{\sigma}_u^2}{\lambda_r} \xrightarrow{\mathcal{P}} 1 \quad \text{and} \quad \frac{\widehat{\lambda}}{\lambda_f} \xrightarrow{\mathcal{P}} 1.$$

Moreover,

$$\lambda_r^{-1/(4q)} \left( \frac{\widehat{\sigma}^2 / \widehat{\sigma}_u^2}{\lambda_r} - 1 \right) \xrightarrow{\mathcal{D}} \mathcal{N}(0, 2C_1(q))$$

and

$$\lambda_f^{-1/(4q)} \left( \frac{\widehat{\lambda}}{\lambda_f} - 1 \right) \xrightarrow{\mathcal{D}} \mathcal{N}(0, 2C_2(q)),$$



## Smoothing parameter estimators

$$C_1(q) = c_\rho \operatorname{sinc}\{\pi/(2q)\} \frac{q}{12q^2 - 3}$$

$$C_2(q) = c_\rho \operatorname{sinc}\{\pi/(2q)\} \frac{q(12q^2 + 8q + 1)}{15(8q^2 - 2q - 1)}$$

- $c_\rho$  depends on the design density  $\rho$
- $C_1(q)$  decreases with  $q$
- $C_2(q)$  increases with  $q$
- $C_2(q)/C_1(q)$  grows fast with  $q$



## Smoothing parameter estimators

$$\text{var} \left( \frac{\hat{\lambda}}{\lambda_f} \right) = O \left( n^{-\frac{1}{2qm+1}} \right), \quad m \in [1, 2]$$
$$\text{var} \left( \frac{\hat{\sigma}^2 / \hat{\sigma}_u^2}{\lambda_r} \right) = O \left( n^{-\frac{1}{2q+1}} \right)$$

- the convergence rate of  $\hat{\lambda}/\lambda_f$  and  $\hat{\sigma}^2/(\lambda_r \hat{\sigma}_u^2)$  to 1 is very slow
- $\hat{\lambda}/\lambda_f$  converge more slowly for smoother functions



## Smoothing parameter estimators

$$\frac{\text{var}(\hat{\lambda})}{\text{var}(\hat{\sigma}^2/\hat{\sigma}_u^2)} \approx q(q+2) \left( \frac{\lambda_f}{\lambda_r} \right)^{2+1/(2q)}$$

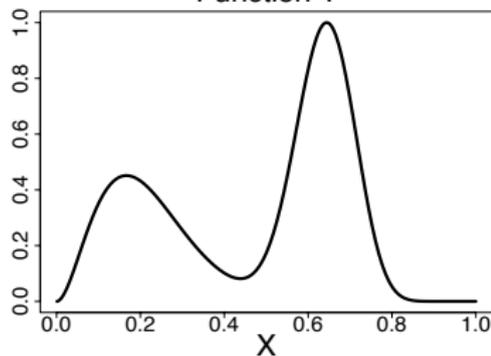
That is due to  $\lambda_f/\lambda_r \rightarrow \infty, n \rightarrow \infty$

- $\text{var}(\hat{\lambda}_f)/\text{var}(\hat{\sigma}^2/\hat{\sigma}_u^2)$  is large and grows with  $q$  and  $n$
- $\hat{f}(\hat{\sigma}^2/\hat{\sigma}_u^2)$  is much more stable than  $\hat{f}(\hat{\lambda}_f)$

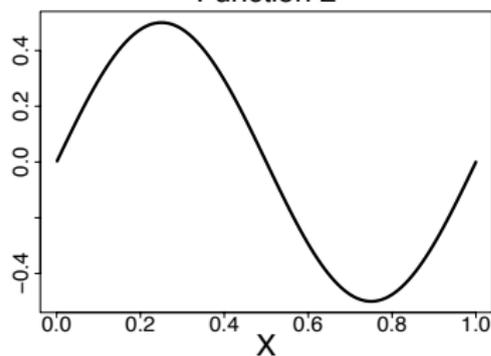


# Simulations $q = 2$

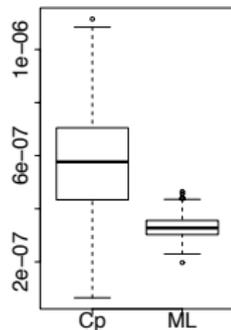
## Function 1



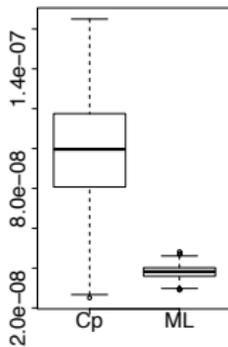
## Function 2



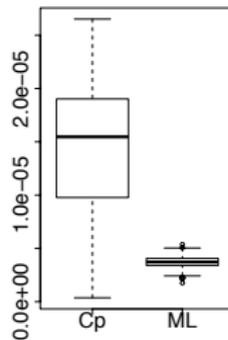
**n=350**



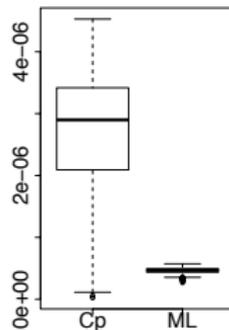
**n=1000**



**n=350**



**n=1000**





## Simulations

Simulation results show

- $\hat{\lambda}$  is much more variable than  $\hat{\sigma}^2/\hat{\sigma}_u^2$
- $\lambda_f/\lambda_r > 1$  and grows with  $n$
- for a periodic  $f_2$ ,  $\lambda_f/\lambda_r$  is larger than for  $f_1$
- in small samples  $\hat{f}(\hat{\lambda})$ ,  $\hat{f}(\hat{\sigma}^2/\hat{\sigma}_u^2)$  perform comparable for  $f_1$

	$n = 350$		$n = 1000$	
	$f_1$	$f_2$	$f_1$	$f_2$
$\frac{R(\hat{f}(\hat{\lambda}), f)}{R(\hat{f}(\hat{\sigma}^2/\hat{\sigma}_u^2), f)}$	1.02	0.99	0.90	0.80



## Data-driven $q$

Large ratio  $\lambda_f/\lambda_r$  suggests that  $f$  is smoother than assumed  $\mathcal{W}^q[0, 1]$

If  $q$  can be chosen data-driven, such that  $\lambda_f/\lambda_r \approx 1$  for given  $n$  and  $f$ , then  $\hat{\sigma}^2/\hat{\sigma}_u^2$  should outperform  $\hat{\lambda}$  due to much smaller variance

One possible way is to choose  $q$  such that

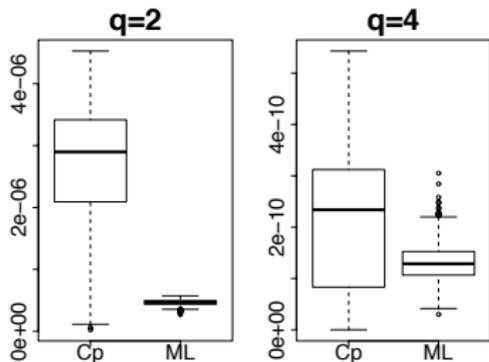
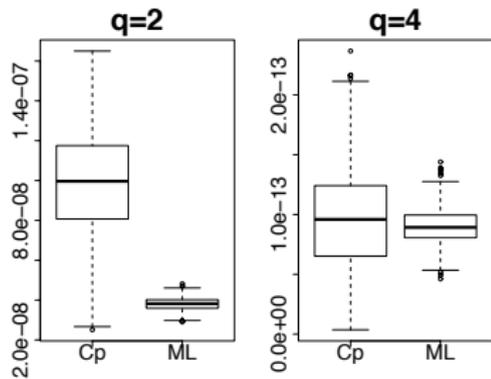
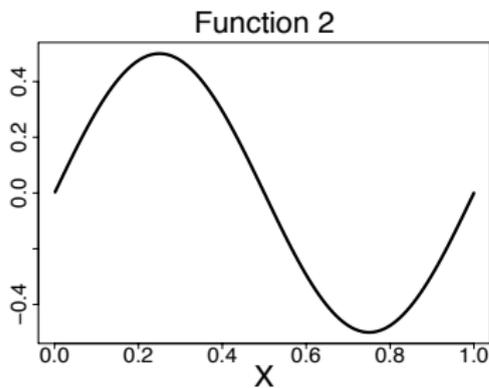
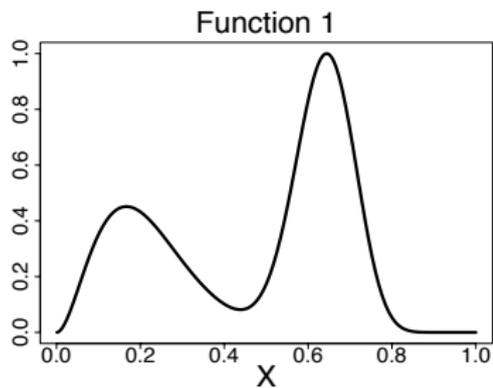
$$R(q) = |Y^t(I_n - S)S^2Y - \hat{\sigma}^2\{\text{tr}(S^2) - q\}|$$

is smallest; here  $S = S(\hat{\sigma}^2/\hat{\sigma}_u^2)$  is the smoother matrix

This criterion is obtained comparing estimating equations of both smoothing parameters



# Simulations $n = 1000$





## Conclusion

- $\lambda_f/\lambda_r$  grows with  $n$
- $\lambda_f$  is able to adapt to the unknown smoothness (up to  $2q$ )
- performance of  $\lambda_r$  depends on  $n$  and  $q$
  
- $\hat{\lambda}$  and  $\hat{\sigma}^2/\hat{\sigma}_u^2$  are both consistent and asymptotically normal
- convergence rate of  $\hat{\lambda}$  and  $\hat{\sigma}^2/\hat{\sigma}_u^2$  is very slow
- $\hat{\lambda}$  converges to  $\lambda$  slower for smoother functions
- constants in asymptotic variances of  $\hat{\lambda}$  and  $\hat{\sigma}^2/\hat{\sigma}_u^2$  are obtained
  
- taking a larger  $q$  can improve the performance of  $\hat{\sigma}^2/\hat{\sigma}_u^2$
- data-driven choice of  $q$  is interesting direction for further research